Introduction

The SPEEDTRONIC™ Mark VI turbine control is the current state-of-the-art control for GE turbines that have a heritage of more than 30 years of successful operation. It is designed as a complete integrated control, protection, and monitoring system for generator and mechanical drive applications of gas and steam turbines. It is also an ideal platform for integrating all power island and balance-of-plant controls. Hardware and software are designed with close coordination between GE's turbine design engineering and controls engineering to insure that your control system provides the optimum turbine performance and you receive a true "system" solution. With Mark VI, you receive the benefits of GE's unmatched experience with an advanced turbine control platform. (*See Figure 1.*)

- Over 30 years experience
- Complete control, protection, and monitoring
- Can be used in variety of applications
- Designed by GE turbine and controls engineering

Figure 1. Benefits of Speedtronic™ Mark VI

Architecture

The heart of the control system is the Control Module, which is available in either a 13- or 21 slot standard VME card rack. Inputs are received by the Control Module through termination boards with either barrier or box-type terminal blocks and passive signal conditioning.

Each I/O card contains a TMS320C32 DSP processor to digitally filter the data before conversion to 32 bit IEEE-854 floating point format. The data is then placed in dual port memory that is accessible by the on-board C32 DSP on one side and the VME bus on the other.

In addition to the I/O cards, the Control Module contains an "internal" communication card, a main processor card, and sometimes a flash disk card. Each card takes one slot except for the main processor that takes two slots. Cards are manufactured with surface-mounted technology and conformal coated per IPC-CC-830.

I/O data is transmitted on the VME backplane between the I/O cards and the VCMI card located in slot 1. The VCMI is used for "internal" communications between:

- I/O cards that are contained within its card rack
- I/O cards that may be contained in expansion I/O racks called Interface Modules
- \blacksquare I/O in backup <P> Protection Modules
- I/O in other Control Modules used in triple redundant control configurations
- The main processor card

The main processor card executes the bulk of the application software at 10, 20, or 40 ms depending on the requirements of the application. Since most applications require that spe-

cific parts of the control run at faster rates (i.e. servo loops, pyrometers, etc.), the distributed processor system between the main processor and the dedicated I/O processors is very important for optimum system performance. A QNX operating system is used for real-time applications with multi-tasking, priority-driven preemptive scheduling, and fast-context switching.

Communication of data between the Control Module and other modules within the Mark VI control system is performed on IONet. The VCMI card in the Control Module is the IONet bus master communicating on an Ethernet 10Base2 network to slave stations. A unique poling type protocol (Asynchronous Drives Language) is used to make the IONet more deterministic than traditional Ethernet LANs. An optional Genius Bus™ interface can be provided on the main processor card in Mark VI Simplex controls for communication with the GE Fanuc family of remote I/O blocks. These blocks can be selected with the same software configuration tools that select Mark VI I/O cards, and the data is resident in the same database.

The Control Module is used for control, protection, and monitoring functions, but some applications require backup protection. For example, backup emergency overspeed protection is always provided for turbines that do not have a mechanical overspeed bolt, and backup synch check protection is commonly provided for generator drives. In these applications, the IONet is extended to a Backup Protection Module that is available in Simplex and triple redundant forms. The triple redundant version contains three independent sections (power supply, processor, I/O) that can be replaced while the turbine is running. IONet is used to access diagnostic data or for cross-tripping between the Control Module and the

Protection Module, but it is not required for tripping.

Triple Redundancy

Mark VI control systems are available in Simplex and Triple Redundant forms for small applications and large integrated systems with control ranging from a single module to many distributed modules. The name Triple Module Redundant (TMR) is derived from the basic architecture with three completely separate and independent Control Modules, power supplies, and IONets. Mark VI is the third generation of triple redundant control systems that were pioneered by GE in 1983. System throughput enables operation of up to nine, 21-slot VME racks of I/O cards at 40 ms including voting the data. Inputs are voted in software in a scheme called Software Implemented Fault Tolerance (SIFT). The VCMI card in each Control Module receives inputs from the Control Module back-plane and other modules via "its own" IONet.

Data from the VCMI cards in each of the three Control Modules is then exchanged and voted prior to transmitting the data to the main processor cards for execution of the application software. Output voting is extended to the turbine with three coil servos for control valves and 2 out of 3 relays for critical outputs such as hydraulic trip solenoids. Other forms of output voting are available, including a median select of 4-20ma outputs for process control and 0- 200ma outputs for positioners.

Sensor interface for TMR controls can be either single, dual, triple redundant, or combinations of redundancy levels. The TMR architecture supports riding through a single point failure in the electronics and repair of the defective card or module while the process is running. Adding sensor redundancy increases the fault tolerance

of the overall "system." Another TMR feature is the ability to distinguish between field sensor faults and internal electronics faults. Diagnostics continuously monitor the 3 sets of input electronics and alarms any discrepancies between them as an internal fault versus a sensor fault. In addition, all three main processors continue to execute the correct "voted" input data. (*See Figure 2.*)

Figure 2. Mark VI TMR control configuration

I/O Interface

There are two types of termination boards. One type has two 24-point, barrier-type terminal blocks that can be unplugged for field maintenance. These are available for Simplex and TMR controls. They can accept two 3.0 mm^2 (#12AWG) wires with 300 volt insulation. Another type of termination board used on Simplex controls is mounted on a DIN rail and has one, fixed, box-type terminal block. It can accept one 3.0 mm2 (#12AWG) wire or two 2.0 mm² (#14AWG) wires with 300 volt insulation.

I/O devices on the equipment can be mounted up to 300 meters (984 feet) from the termination boards, and the termination boards must be within 15 m (49.2') from their corresponding I/O cards. Normally, the termination boards are mounted in vertical columns in termination cabinets with pre-assigned cable lengths and routing to minimize exposure to emi-rfi for noise sensitive signals such as speed inputs and servo loops.

General Purpose I/O

Discrete I/O. A VCRC card provides 48 digital inputs and 24 digital outputs. The I/O is divided between 2 Termination Boards for the contact inputs and another 2 for the relay outputs. (*See Table 1.*)

Analog I/O. A VAIC card provides 20 analog inputs and 4 analog outputs. The I/O is divided between 2 Termination Boards. A VAOC is dedicated to 16 analog outputs and interfaces with 1 barrier-type Termination Board or 2 box-type Termination Boards. (*See Table 2.*)

Temperature Monitoring. A VTCC card provides interface to 24 thermocouples, and a VRTD card provides interface for 16 RTDs. The input cards interface with 1 barrier-type

| TB | Type | VO | Characteristics | |
|-------------|-------------|-----------|---|--|
| TBCI | Barrier | 24 CI | 70-145 Vdc, optical isolation, 1 ms SOE | |
| | | | 2.5ma/point except last 3 input are 10ma / point | |
| DTCI | Box | 24 CI | 18-32Vdc, optical isolation, 1ms SOE | |
| | | | 2.5ma/point except last 3 input are 10ma/point | |
| TICI | Barrier | 24 CI | 70-145Vdc, 200-250Vdc, 90-132Vrms, 190-264Vrms (47-63Hz), optical isolation 1ms SOE, 3ma / point | |
| TRLY | Barrier | 12 CO | Plug-in, magnetic relays, dry, form "C" contacts | |
| | | | 6 circuits with fused 3.2A, suppressed solenoid outputs | |
| | | | Form H1B: diagnostics for coil current | |
| | | | Form H1C: diagnostics for contact voltage | |
| | | | Voltage Resistive Inductive | |
| | | | 24Vdc 3.0 _A 3.0 amps $L/R = 7$ ms, no suppr. | |
| | | | 3.0 amps $L/R = 100$ ms, with suppr | |
| | | | 125Vdc 0.6A 0.2 amps $L/R = 7$ ms, no suppr. | |
| | | | 0.6 amps $L/R = 100$ ms, with suppr | |
| | | | 120/240Vac 6/3A 2.0 amps $pf = 0.4$ | |
| DRLY | Box | 12 CO | Same as TRLY, but no solenoid circuits | |

Table 1. Discrete I/O

| TB | Type | IO | Characteristics | |
|-------------|-------------|------------------|--|--|
| TBAI | Barrier | 10 AI | (8) 4-20ma (250 ohms) or $+/-5,10$ Vdc inputs | |
| | | 2. AO | (2) 4-20ma (250 ohms) or $+/-1$ ma (500 ohms) inputs | |
| | | | Current limited +24Vdc provided per input | |
| | | | $(2) +24V$, 0.2A current limited power sources | |
| | | | (1) 4-20ma output (500 ohms) | |
| | | | (1) 4-20ma (500 ohms) or 0-200ma (50 ohms) output | |
| TBAO | Barrier | 16 AO | (16) 4-20ma outputs (500 ohms) | |
| DTAI | Box | 10 AI | (8) 4-20ma (250 ohms) or $+/-5,10$ Vdc inputs | |
| | | 2 A ₀ | (2) 4-20ma (250 ohms) or $+/-1$ ma (500 ohms) inputs | |
| | | | Current limited +24Vdc available per input | |
| | | | (1) 4-20ma output (500 ohms) | |
| | | | (1) 4-20ma (500 ohms) or 0-200ma (50 ohms) output | |
| DTAO | Box | 8 AO | (8) 4-20ma outputs (500 ohms) | |

Table 2. Analog I/O

Termination Board or 2 box-type Termination Boards. Capacity for monitoring 9 additional thermocouples is provided in the Backup Protection Module. (*See Table 3.*)

| TB | Type | U ^O | Characteristics |
|-------------|------------|------------------|---|
| TBTC | Barrier | 24 TC | Types: E, J, K, T, grounded or ungrounded H1A fanned (paralleled) inputs, H1B dedicated inputs |
| DTTC | Box | 12 TC | Types: E, J, K, T, grounded or ungrounded |
| TRTD | Barrier | 16 RTD | 3 points/RTD, grounded or ungrounded 10 ohm copper, 100/200 ohm platinum, 120 ohm nick H1A fanned (paralleled) inputs, H1B dedicated inputs |
| DTAI | Box | 8 RTD | RTDs, 3 points/RTD, grounded or ungrounded 10 ohm copper, 100/200 ohm platinum, 120 ohm nick |

Table 3. Temperature Monitoring

Application Specific I/O

In addition to general purpose I/O , the Mark VI has a large variety of cards that are designed for direct interface to unique sensors and actuators. This reduces or eliminates a substantial amount of interposing instrumentation in many applications. As a result, many potential single-point failures are eliminated in the most critical area for improved running reliability and reduced long-term maintenance. Direct interface to the sensors and actuators also enables the diagnostics to directly interrogate the devices on the equipment for maximum effectiveness. This data is used to analyze device and system performance. A subtle benefit of this design is that spare-parts inventories are

reduced by eliminating peripheral instrumentation. The VTUR card is designed to integrate several of the unique sensor interfaces used in turbine control systems on a single card. In some applications, it works in conjunction with the I/O interface in the Backup Protection Module described below.

Speed (Pulse Rate) Inputs. Four-speed inputs from passive magnetic sensors are monitored by the VTUR card. Another two-speed (pulse rate) inputs can be monitored by the servo card VSVO which can interface with either passive or active speed sensors. Pulse rate inputs on the VSVO are commonly used for flow-divider feedback in servo loops. The frequency range is 2- 14k Hz with sufficient sensitivity at 2 Hz to detect zero speed from a 60-toothed wheel. Two additional passive speed sensors can be monitored by "each" of the three sections of the Backup Protection Module used for emergency overspeed protection on turbines that do not have a mechanical overspeed bolt. IONet is used to communicate diagnostic and process data between the Backup Protection Module and the Control Module(s) including cross-tripping capability; however, both modules will initiate system trips independent of the IONet. (*See Table 4 and Table 5.*)

Synchronizing. The synchronizing system consists of automatic synchronizing, manual synchronizing, and backup synch check protection. Two single-phase PT inputs are provided

| TB | Type | I/O | Characteristics | |
|-------------|------------|---|---|--|
| TTUR | Barrier | 4 Pulse rate | Passive magnetic speed sensors (2-14k Hz) | |
| | | 2 PTs | Single phase PTs for synchronizing | |
| | | Synch relays | Auto/Manual synchronizing interface | |
| | | 2 SVM | Shaft voltage / current monitor | |
| TRPG* | Barrier | 3 Trip solenoids | (-) side of interface to hydraulic trip solenoids | |
| TRPS* | | 8 Flame inputs | UV flame scanner inputs (Honeywell) | |
| TRPL* | | | | |
| DTUR | Box | 4 Pulse Rate | Passive magnetic speed sensors (2-14k Hz) | |
| DRLY | Box | 12 Relays Form "C" contacts - previously described | | |
| DTRT | | | Transition board between VTUR & DRLY | |

Table 4. VTUR I/O terminations from Control Module

Table 5. VPRO I/O terminations from Backup Protection Module

on the TTUR Termination Board to monitor the generator and line busses via the VTUR card. Turbine speed is matched to the line frequency, and the generator and line voltages are matched prior to giving a command to close the breaker via the TTUR.

An external synch check relay is connected in series with the internal K25P synch permissive relay and the K25 auto synch relay via the TTUR. Feedback of the actual breaker closing time is provided by a 52G/a contact from the generator breaker (not an auxiliary relay) to update the database. An internal K25A synch check relay is provided on the TTUR; however, the backup phase / slip calculation for this relay is performed in the Backup Protection Module or via an external backup synch check relay. Manual synchronizing is available from an operator station on the network or from a synchroscope.

Shaft Voltage and Current Monitor. Voltage can build up across the oil film of bearings until a discharge occurs. Repeated discharge and arcing can cause a pitted and roughened bearing surface that will eventually fail through accelerated mechanical wear. The VTUR / TTUR can continuously monitor the shaft-to- ground voltage and current, and alarm at excessive levels. Test circuits are provided to check the alarm functions and the continuity of wiring to the brush assembly that is mounted between the turbine and the generator.

Flame Detection. The existence of flame either can be calculated from turbine parameters that are already being monitored or from a direct interface to Reuter Stokes or Honeywell-type flame detectors. These detectors monitor the flame in the combustion chamber by detecting UV radiation emitted by the flame. The Reuter Stokes detectors produce a 4-20ma input. For Honeywell flame scanners, the Mark VI supplies the 335Vdc excitation and the VTUR / TRPG monitors the pulses of current being generated. This determines if carbon buildup or other contaminates on the scanner window are causing reduced light detection.

Trip System. On turbines that do not have a mechanical overspeed bolt, the control can issue a trip command either from the main processor card to the VTUR card in the Control Module(s) or from the Backup Protection Module. Hydraulic trip solenoids are wired with the negative side of the 24Vdc/125Vdc circuit connected to the TRPG, which is driven from the VTUR in the Control Module(s) and the positive side connected to the TREG which is driven from the VPRO in each section of the Backup Protection Module. A typical system trip initiated in the Control Module(s) will cause the analog control to drive the servo valve actuators closed, which stops fuel or steam flow and de-energizes (or energizes) the hydraulic trip solenoids from the VTUR and TRPG. If crosstripping is used or an overspeed condition is detected, then the VTUR/TRPG will trip one side of the solenoids and the VPTRO/TREG will trip the other side of the solenoid(s).

Servo Valve Interface. A VSVO card provides 4 servo channels with selectable current drivers, feedback from LVDTs, LVDRs, or ratio metric LVDTs, and pulse-rate inputs from flow divider feedback used on some liquid fuel systems. In TMR applications, 3 coil servos are commonly

used to extend the voting of analog outs to the servo coils. Two coil servos can also be used. One, two, or three LVDT/Rs feedback sensors can be used per servo channel with a high select, low select, or median select made in software. At least 2 LVDT/Rs are recommended for TMR applications because each sensor requires an AC excitation source. (*See Table 6 and Table 7.*)

| TB | Type | I/O | Characteristics |
|-------------|-------------|----------|--------------------------------------|
| TSVO | Barrier | 2 chnls. | (2) Servo current sources |
| | | | (6) LVDT/LVDR feedback |
| | | | 0 to 7.0 Vrms |
| | | | (4) Excitation sources |
| | | | 7 Vrms, 3.2k Hz |
| | | | (2) Pulse rate inputs $(2-14k$ Hz) |
| | | | *only 2 per VSVO |
| DSVO | Box | 2 chnls. | (2) Servo current sources |
| | | | (6) LVDT/LVDR feedback |
| | | | 0 to 7.0 Vrms |
| | | | (2) Excitation sources |
| | | | 7 Vrms, 3.2k Hz |
| | | | (2) Pulse rate inputs $(2-14k$ Hz) |
| | | | *only 2 per VSVO |

Table 6. VSVO I/O terminations from Control Module

| Coil | Nominal | Coil | Mark VI |
|-------------|----------------|-------------------|---------------|
| Type | Current | Resistance | Control |
| #1 | $+/- 10$ ma | 1,000 ohms | Simplex & TMR |
| #2 | $+/- 20$ ma | 125 ohms | Simplex |
| #3 | $+/- 40$ ma | 62 ohms | Simplex |
| #4 | $+/- 40$ ma | 89 ohms | TMR |
| #5 | $+/- 80$ ma | 22 ohms | TMR |
| #6 | $+/- 120$ ma | 40 ohms | Simplex |
| #7 | $+/- 120$ ma | 75 ohms | TMR |

Table 7. Nominal servo valve ratings

Vibration / Proximitor® Inputs. The VVIB card provides a direct interface to seismic (velocity), Proximitor®, Velomitor®, and accelerometer (via charge amplifier) probes. In addition, DC position inputs are available for axial measurements and Keyphasor® inputs are provided. Displays show the 1X and unfiltered vibration levels and the 1X vibration phase angle. -24vdc is supplied from the control to each Proximitor with current limiting per point. An optional ter-

mination board can be provided with active isolation amplifiers to buffer the sensor signals from BNC connectors. These connectors can be used to access real-time data by remote vibration analysis equipment. In addition, a direct plug connection is available from the termination board to a Bently Nevada 3500 monitor. The 16 vibration inputs, 8 DC position inputs, and 2 Keyphasor inputs on the VVIB are divided between 2 TVIB termination boards for 3,000 rpm and 3,600 rpm applications. Faster shaft speeds may require faster sampling rates on the VVIB processor, resulting in reduced vibration inputs from 16-to-8. (*See Table 8.*)

Table 8. VVIB I/O terminations from Control Module

Three phase PT and CT monitoring. The VGEN card serves a dual role as an interface for 3 phase PTs and 1 phase CTs as well as a specialized control for Power-Load Unbalance and Early-Valve Actuation on large reheat steam turbines. The I/O interface is split between the TGEN Termination Board for the PT and CT inputs and the TRLY Termination Board for relay outputs to the fast acting solenoids. 4- 20ma inputs are also provided on the TGEN for monitoring pressure transducers. If an EX2000 Generator Excitation System is controlling the generator, then 3 phase PT and CT data is communicated to the Mark VI on the network rather than using the VGEN card. (*See Table 9*.)

Optical Pyrometer Inputs. The VPYR card moni-